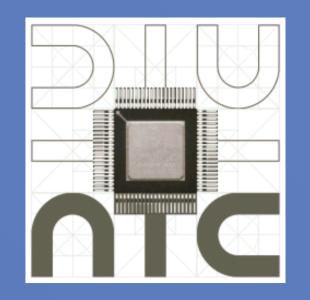


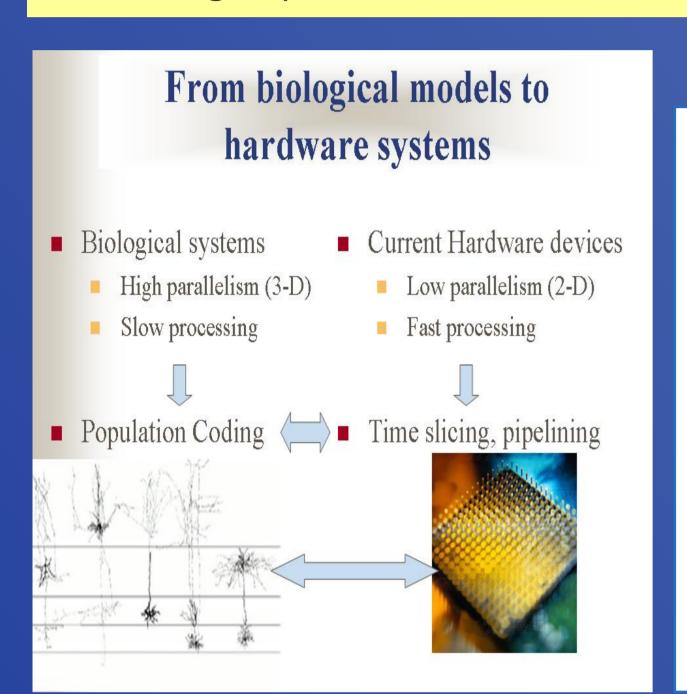
# Low-Middle level vision-on-chip

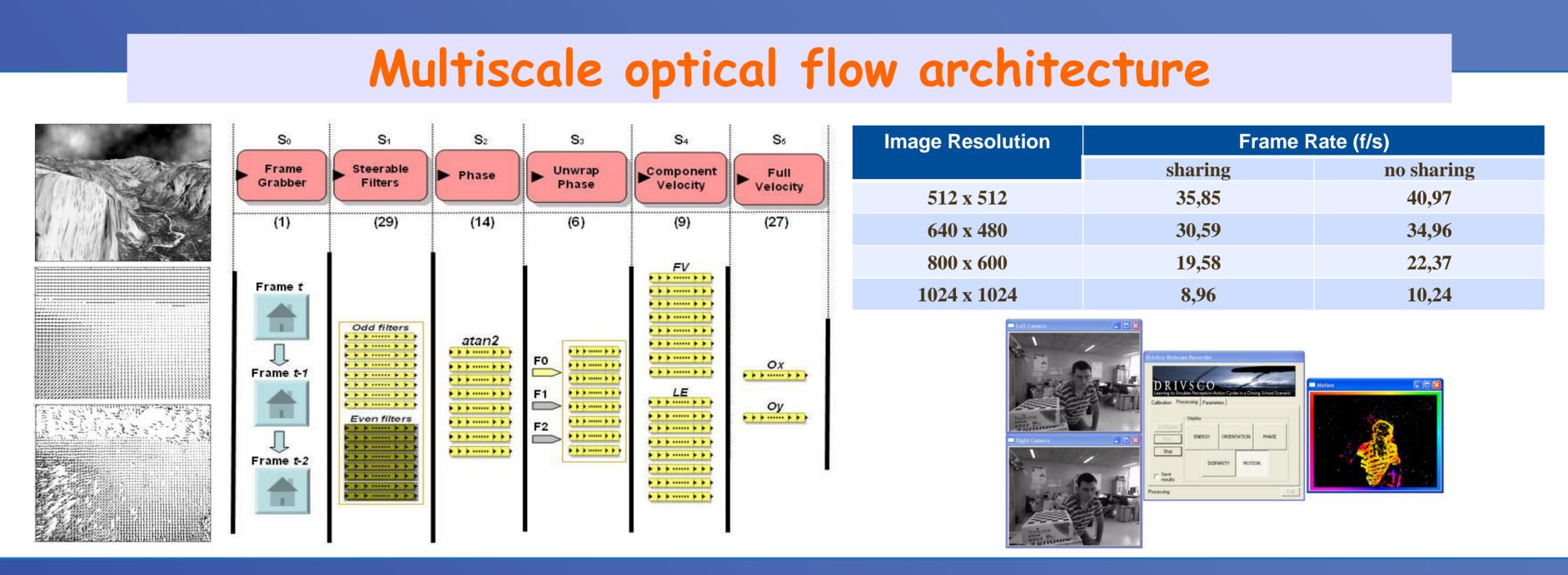


## Javier Díaz., Department of Computer Architecture and Technology. University of Granada. Spain.

**Bio-inspired Vision.** Engineering processing architectures designed for tasks that biological systems solve with impressive ease can benefit considerably by mimicking computing strategies developed by nature. However, the adaptation of such techniques is not straightforward, since the physical principles upon which biological tissues are based are very different from those characteristically used in electronic technology. Nevertheless, an "opportunistic attitude" which takes the key-functional principles that contribute to the outstanding performance of biological systems and also uses technology-motivated computing techniques to adapt those computing primitives must be of considerable interest.

We use these techniques to develop powerful vision sensors for a multiscale, phase based, local features (phase, energy and orientation), motion and stereo-vision processing in real-time. Moreover, we address a simple condensation scheme capable to build sparse multimodal image descriptors with relevant information for middle-high level vision layers. The final system is based on FPGA technology which is suitable to be used on embedded systems, necessary for a large number of robotics and industrial applications, allowing exploration and interaction tasks in real-time attempting to close the perception-action loop.

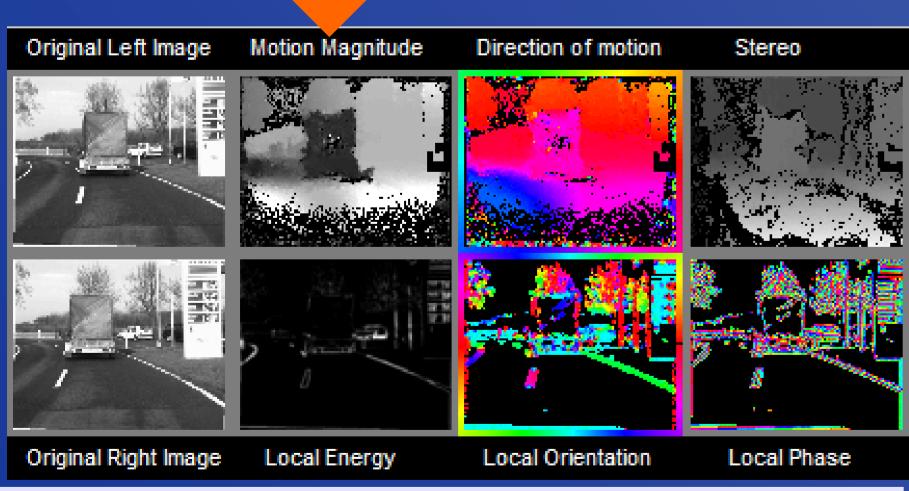




### Processing platform



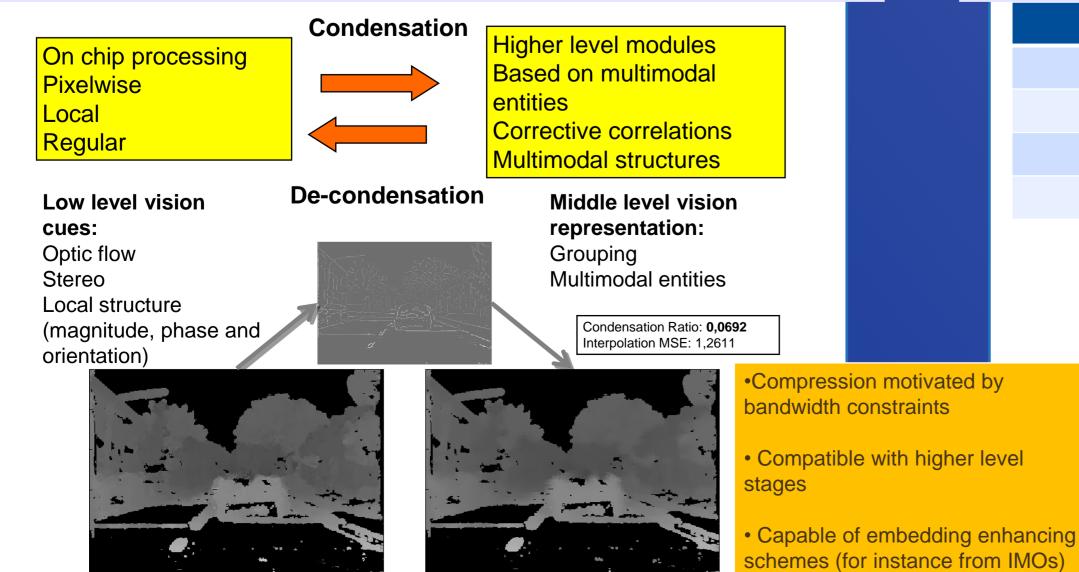
- XircaV4 platform:
- Xilinx Virtex 4 FPGA xc4vfx100
- 4 ZBT memory banks and
- DDR memory
- PCI expressGigabit Ethernet



#### Multiscale stereo architecture

Image Resolution	Frame Rate (f/s)			So		S <sub>1</sub>	S <sub>2</sub>
	3 banks/sharing	3 banks/ no sharing	4 banks		Steerable Filters	(Crossed filter	Merge Orientation
512 x 512	34,74	45,84	67,39			response)	
640 x 480	29,64	39,12	57,51		(29)	(21)	(9)
800 x 600	18,97	25,04	36,80	Left Camera			1),
1024 x 1024	8,68	11,46	16,84		Even filters	atan2	
Right Sequence Frame	DRIVSCO Webcam Recorder  DRIVSCO Learning for firmulate Perception-Action Cycles in a Dri Calibration Processing Parameters  Configure  ENERGY CRIENTATION Stop  DISPARITY MOTE Save results  Processing	PHASE OF THE PHASE		Right Camera	Odd filters		Median

#### Image features condensation



### Local phase, energy and orientation architecture

