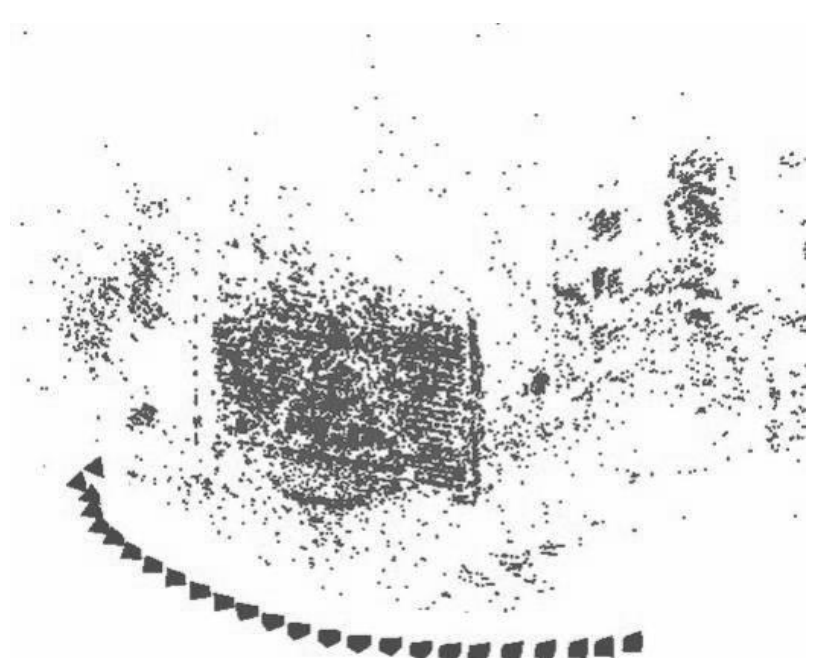


Abstract To obtain high-resolution reconstructions from a large-scale object using SfM, there are many constraints on the quality of image data. In traditional SfM methods, images are acquired at a constant distance to the object which introduces significant drift that cannot be reduced by even bundle adjustment. In this work, we propose to adjust the image acquisition strategy to a multi-scale network and take images at different distances to obtain dense reconstructions while being more accurate.

Motivation



In traditional SfM methods [1] images are acquired at a constant distance

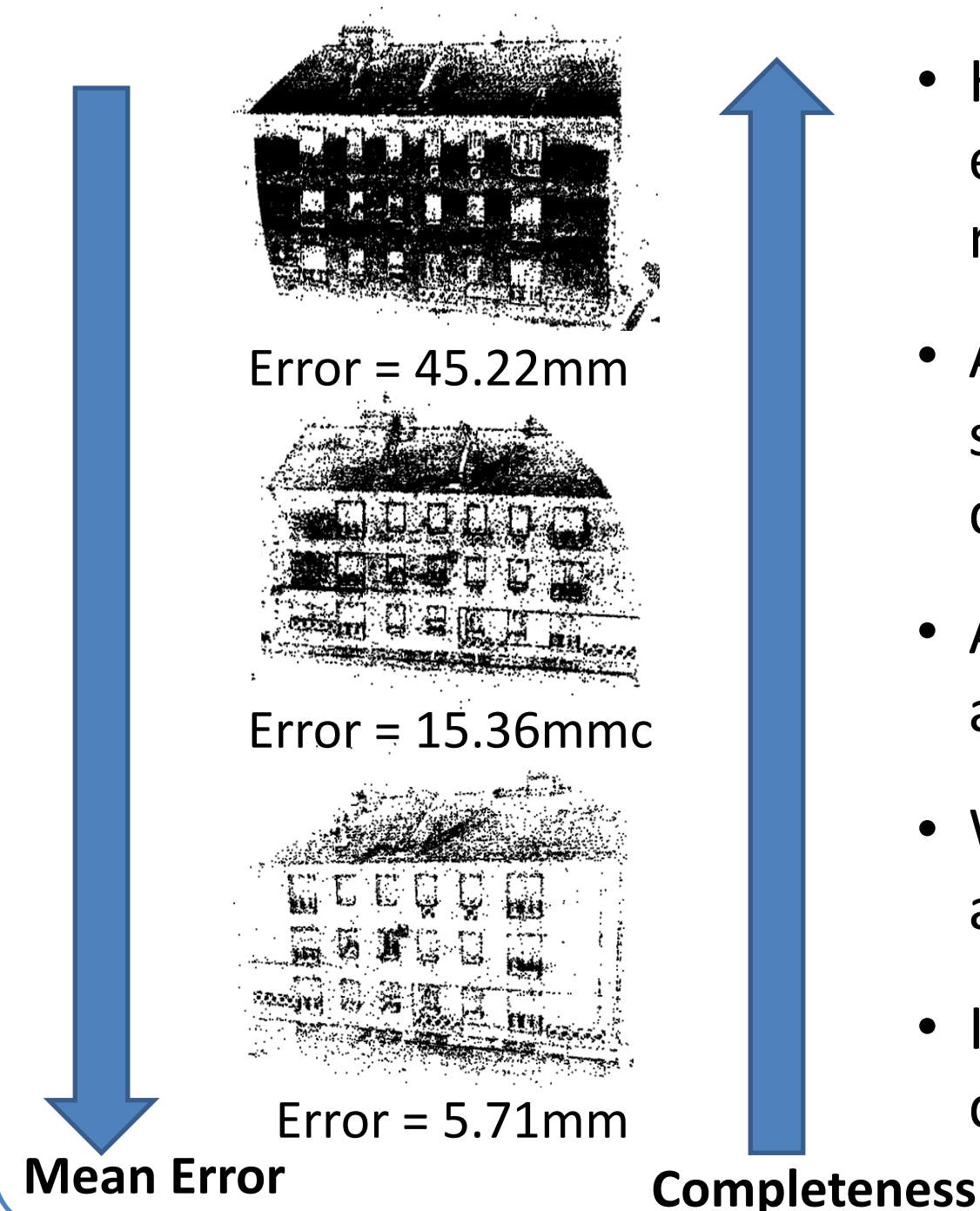
- How to obtain high accuracy and scene completeness of 3D reconstruction at same time?
- How to support the user during image acquisition and view planning to provide robust input data?
- How to remove the problem of drift in Incremental SfM methods?
- No dataset with images at multiple depth and complete ground-truth currently available

Our Contributions

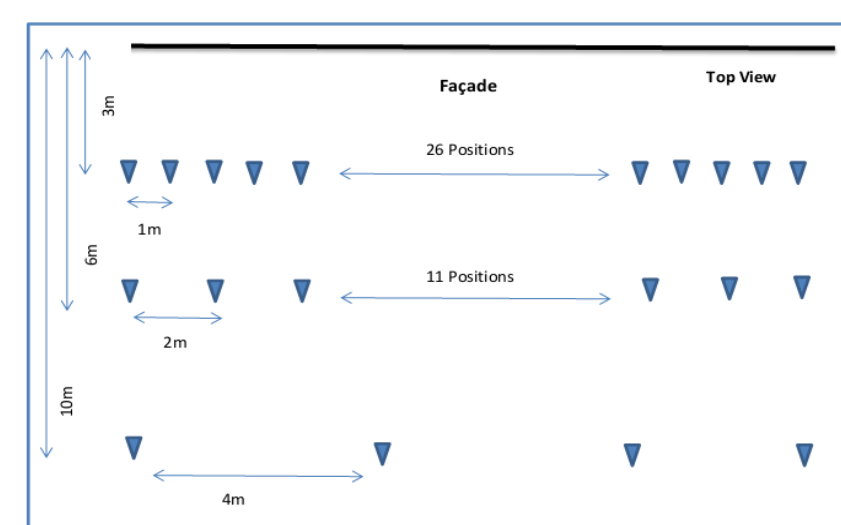
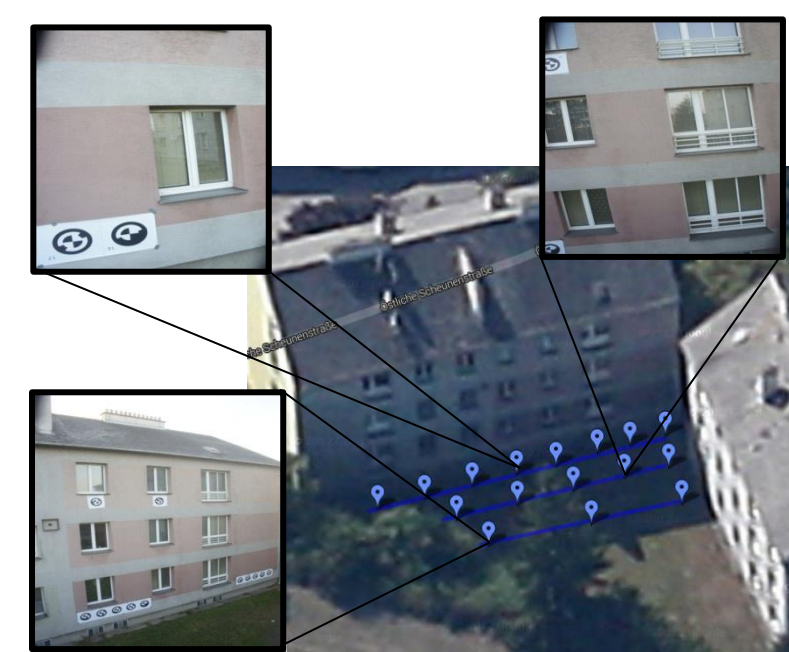
- **The first system for exploring multi-scale camera network for SfM.**
- **Online feedback during image acquisition to end users for planning suitable views.**
- **Novel method for drift removal in Incremental SfM.**
- **A benchmarking dataset and evaluation w.r.t state of the art pipelines and commercial softwares.**

Multi-Scale Camera Network

Scene Completeness Vs. High Accuracy



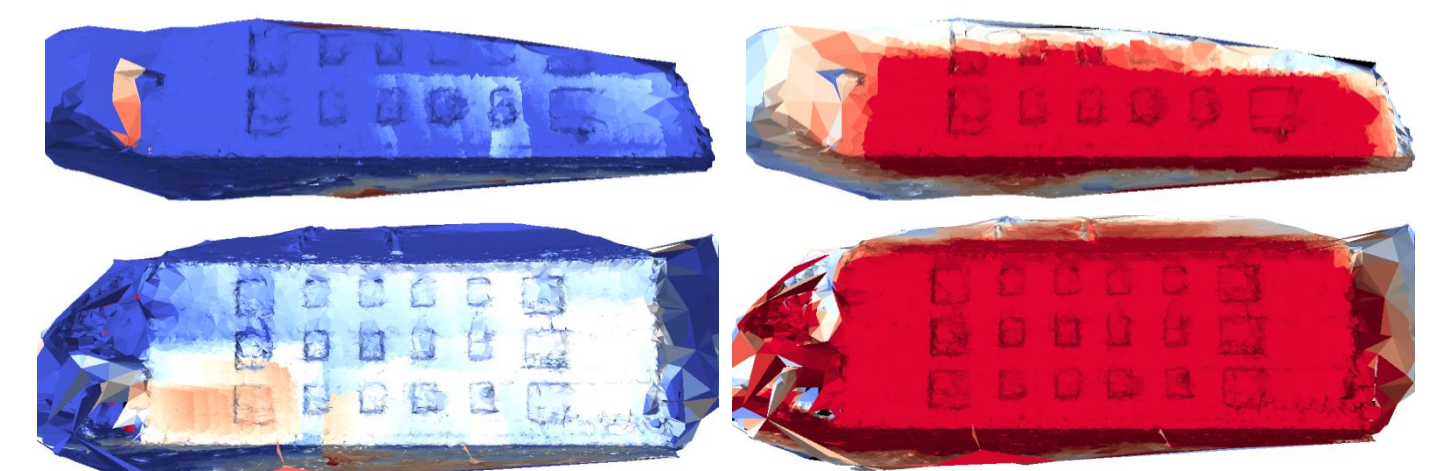
- High resolution images is expected to give "better" reconstruction.
- As we go closer to an object, scene completeness increases due to high GSD.
- Accuracy decreases significantly as affects due to drift increases.
- We use a multi scale frame work as shown to preserve both.
- Image overlap is kept constant at different scales.



An example of multi-scale image acquisition framework

Online Feedback and View-Planning

- We utilize our online-SfM method [2] to give end-user an instant feedback about GSD (ground sampling distance) and image overlap for view-planning.
- **Benefits:** To ensure that image matching can be performed across multiple scales and fidelity of eventual reconstruction.

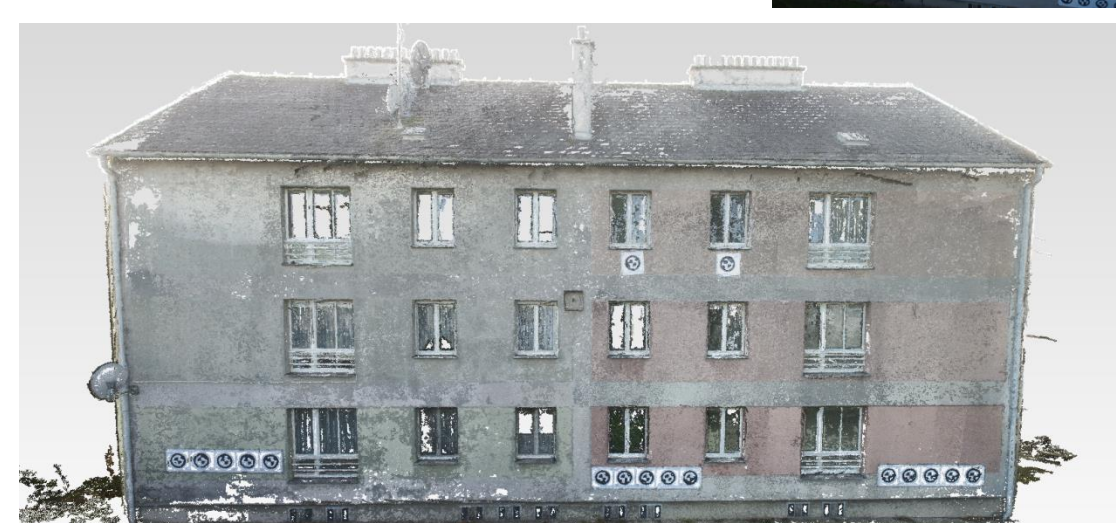
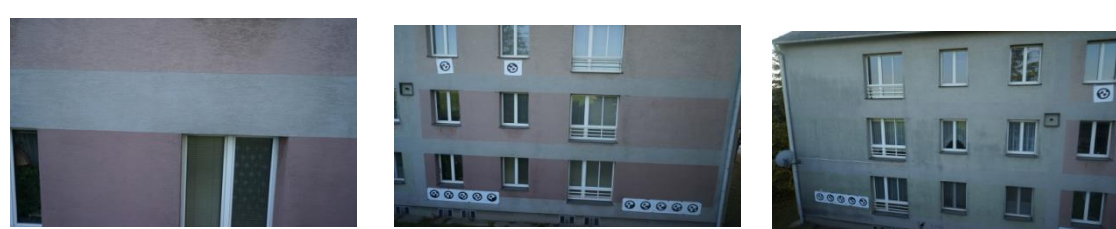


Evolution of the reconstructed façade over time

Performance Evaluation and Results

Benchmarking Dataset

- 1000 images acquired at different depths, heights and angle to façade.
- Ground-truth of urban façade measured with LIDAR.



(a) Images at 4m, 6m and 10m scales.
(b) Dense reconstruction of the Façade.

Quantitative Evaluation

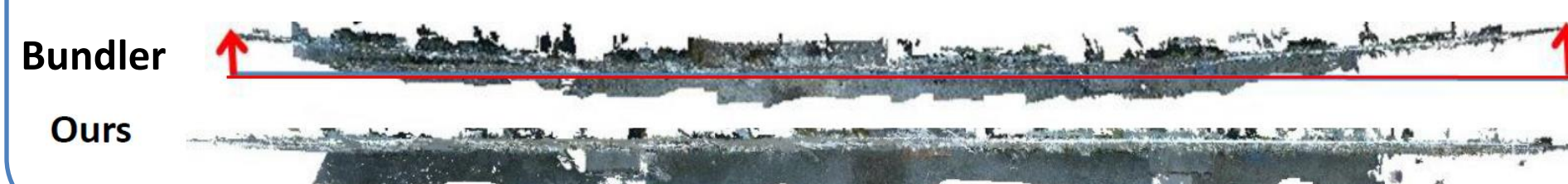
- Visible accuracy gains with online feedback during image-acquisition and quality measures during planning.

	Ours	Bundler [3]	Agisoft®
Mean Error	8.02mm	15.5mm	21.55mm

(GCP measured with Theodolite with uncertainty ~1mm)

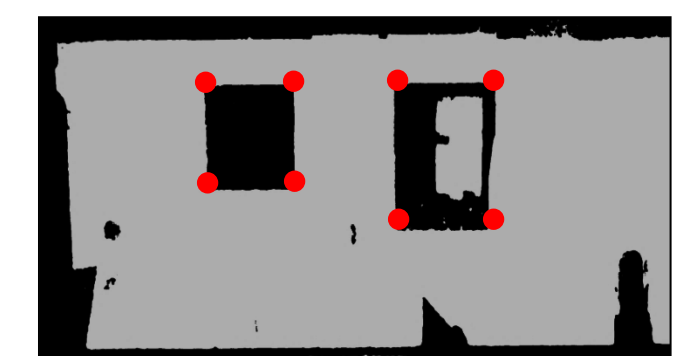
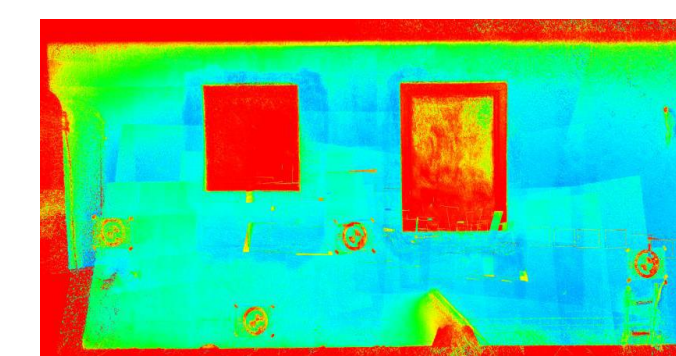
Geometric Fidelity of Reconstruction

- Significant bends and drift along fringes using bundler [3]
- Using the Multi-Scale Acquisition framework we get straight wall reconstruction.



Application to Façade Modeling

- Automatic segmentation of façade and window/door detection with high accuracy.
- Multi-scale acquisition gives accurate and complete data required for such application



(a) Façade probability map (b) window detection result

	L. Window	R. Window
Ground Truth	107.3 cm	119.7 cm
Reconstructed	107.1 cm	120.0 cm
Mean Error	0.25 cm	

Mean Error in Façade element detection

References

- [1] C. Stretcha *et al.* On Benchmarking Camera Calibration and MVS. for High Resolution Imagery, CVPR'08
- [2] C. Hoppe *et al.*, Online Feedback for Structure-from-Motion Image Acquisition, BMVC'12
- [3] N. Snavely *et al.*, Modeling the World from Internet Photo Collections, IJCV'07

Acknowledgement

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